

The field line map approach to plasma turbulence simulations

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- 4 Outlook and summary

Motivation

Ultimate goal

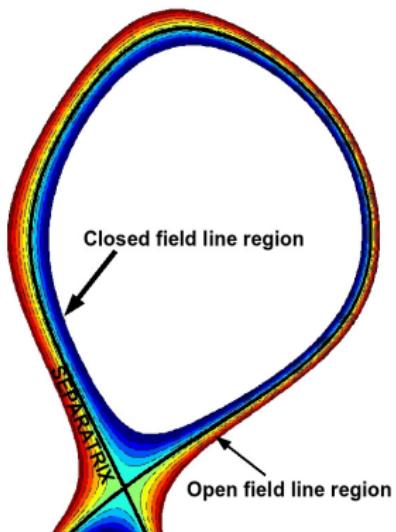
Prediction/Computation of anomalous transport/turbulence in edge and scrape-off layer

Why?

- Boundary region may have high influence on overall performance of reactor [Stangeby90, McCracken93]
- Many phenomena occurring in edge/SOL not yet fully understood
- Prediction of heat loads on divertor plates

Major challenges

- ① Complex physical model
- ② Complex geometry



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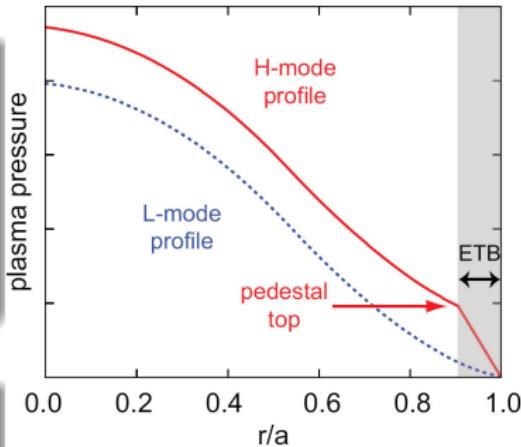
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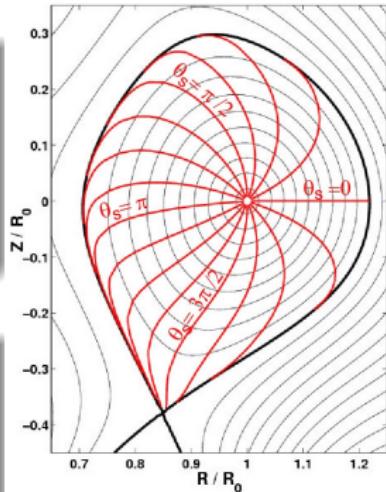
- ① Complex physical model
- ② Complex geometry



Coordinates

Field-aligned coordinates [D'haeseleer et al.90]

- Structures strongly elongated along field lines $k_{\parallel} \ll k_{\perp}$
- Scale separation via transformation to field-aligned coordinates/grids
- **BUT: ILL DEFINED ON SEPARATRIX**



Flux-aligned coordinates

- Ill defined on X/O-point [Matter95], can be circumvented numerically
- However: X-point remains 'special', resolution imbalance

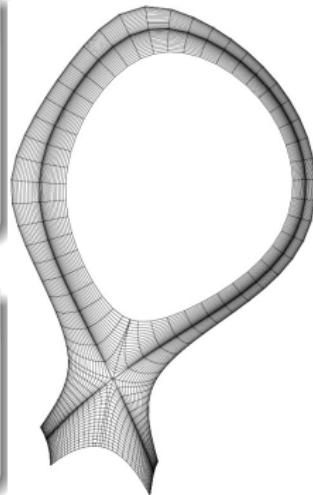
Goal

- Development and implementation of numerical concept, which avoids field/flux-aligned coordinates → applicable to separatrix
- Application to simplified plasma turbulence model

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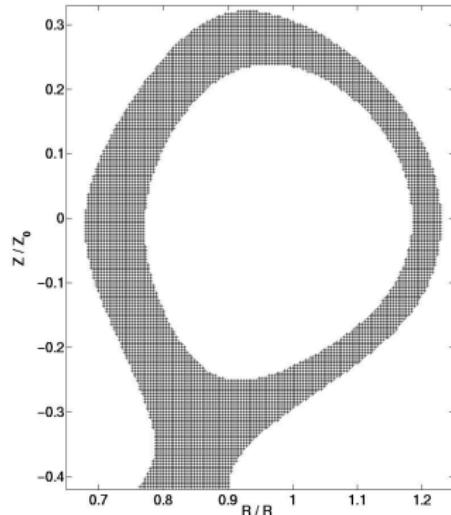
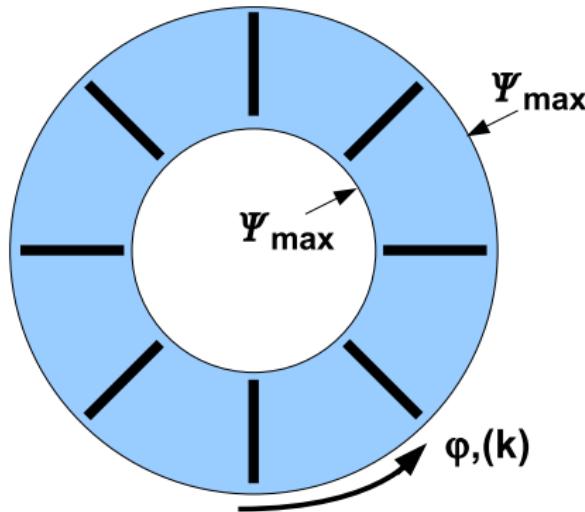
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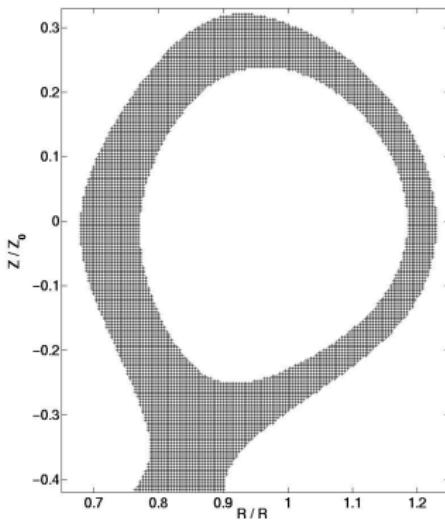
Overview

- See Flux Coordinate Independent approach (FCI) [Ottaviani11, Hariri and Ottaviani13, Hariri et al.14], F. Hariri's talk on Tuesday
- Cylindrical grid $R_i, Z_j, \varphi_k \rightarrow$ no singularities¹ or special points
- Fieldline-following discretisation for parallel operators
- Grid sparsification in toroidal direction ($k_{\parallel} \ll k_{\perp}$)



¹in relevant region

Perpendicular operators



Assumption $B_{tor} \gg B_{pol}$

- Stencil remains within poloidal plane
- Use of standard finite-difference methods

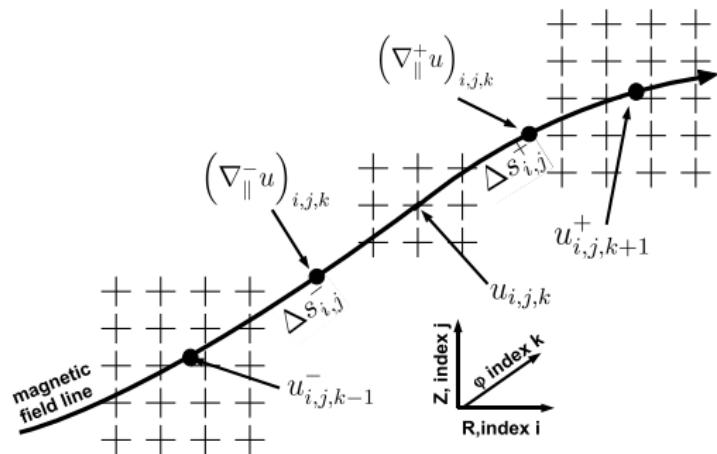
Parallel operators

- Stencil covers neighbouring poloidal planes
- Discretisation via finite difference along magnetic field lines
- Fieldline tracing and interpolation

$$R^\pm = \int_0^{\pm\Delta\varphi} \frac{B^R}{B^\varphi} d\varphi, Z^\pm = \int_0^{\pm\Delta\varphi} \frac{B^Z}{B^\varphi} d\varphi,$$

$$(\nabla_{\parallel}^{\pm} u)_{i,j,k} = \pm \frac{u_{i,j,k\pm 1}^{\pm} - u_{i,j,k}}{\Delta s_{i,j}^{\pm}},$$

$u_{i,j,k}^{\pm}$ via 2D interpolation



- Express via matrices \mathbf{Q}^{\pm} , i.e.:

$$\mathbf{q}^{\pm} = \mathbf{Q}^{\pm} \mathbf{u}$$

$$\mathbf{q}^{\pm} := \left((\nabla_{\parallel}^{\pm} u)_{1,1,1}, (\nabla_{\parallel}^{\pm} u)_{2,1,1}, \dots \right), \quad \mathbf{u} := (u_{1,1,1}, u_{2,1,1}, \dots)$$

Parallel diffusion

$$\mathcal{D}_{\parallel} u := \nabla \cdot [\mathbf{b} (\nabla_{\parallel} u)]$$

Naive scheme

- Assume: $\mathcal{D}_{\parallel} \approx \nabla_{\parallel}^2$
- Discretisation via further finite difference along magnetic field lines:

$$(\mathcal{D}_{\parallel}^{naive} u)_{i,j,k} = \frac{2}{\Delta s_{i,j}^+ + \Delta s_{i,j}^-} [\nabla_{\parallel}^+ u_{i,j,k} - \nabla_{\parallel}^- u_{i,j,k}]$$

- However: Better scheme possible

Parallel diffusion: Support operator method

- Motivated from [Günter et al. (2005 and 2007)]
- Construct scheme which mimics 'good' property on discrete level, i.e. self-adjointness ($u, v = 0$ at boundaries):

$$\begin{aligned}\langle u, \mathcal{D}_{\parallel} v \rangle &= \int_V u \nabla \cdot [\mathbf{b} (\nabla_{\parallel} v)] dV = - \int_V \nabla_{\parallel} u \nabla_{\parallel} v dV \\ \rightarrow \nabla_{\parallel}^{\dagger} &= -\nabla \cdot [\mathbf{b} \circ], \quad \mathcal{D}_{\parallel}^{\dagger} = \mathcal{D}_{\parallel}\end{aligned}\tag{1}$$

Support operator method [Shaskov (1996)]

Mimic integral equality 1 on discrete level

- ① Define discrete space for scalars SG and fluxes (gradients) FG^{\pm} with corresponding inner product
- ② Define and discretise prime operator: $\nabla_{\parallel} \rightarrow \mathbf{Q}^{\pm} : SG \rightarrow FG^{\pm}$
- ③ Use integral equality 1 to construct derived operator

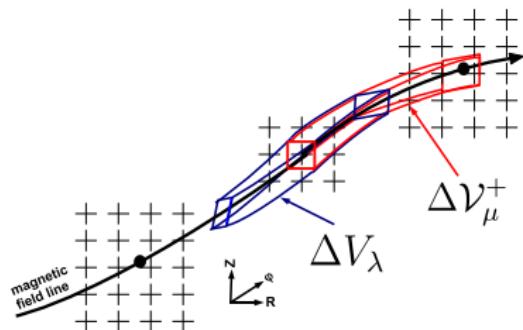
Parallel diffusion: Support operator method

Discrete spaces:

- Scalars SG : cylindrical grid
- Fluxes FG^\pm : staggered along field lines
- Inner products:

$$\langle u, v \rangle_{SG} := \sum_{\lambda} u_{\lambda} v_{\lambda} \Delta V_{\lambda}$$

$$\langle q^{\pm}, p^{\pm} \rangle_{FG^{\pm}} := \sum_{\mu} q_{\mu}^{\pm} p_{\mu}^{\pm} \Delta \mathcal{V}_{\mu}$$



Greek indices denote summation over all grid points

- Two possibilities ' \pm ' (will be combined later)

Parallel diffusion: Support operator method

Discrete parallel gradient, discrete inner products, integral equality



Discrete parallel diffusion operator

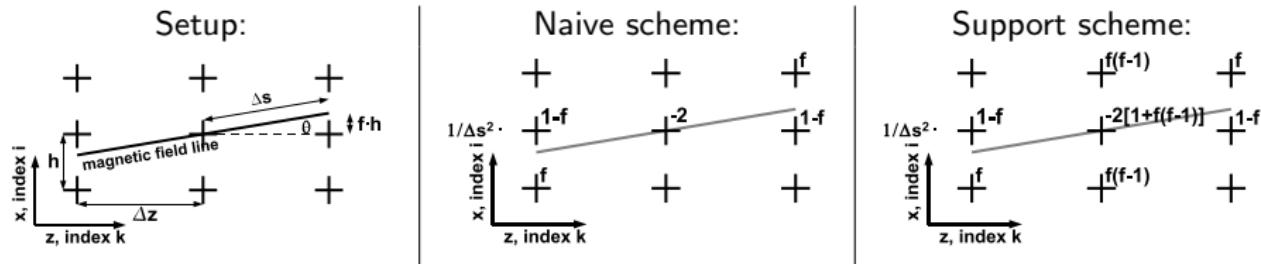
$$\mathbf{D}_{\parallel,\sigma,\lambda}^{\pm,supp} = - \sum_{\mu} \mathbf{Q}_{\mu,\lambda}^{\pm} \mathbf{Q}_{\mu,\sigma}^{\pm} \frac{\Delta V_{\mu}^{\pm}}{\Delta V_{\lambda}}$$

Notes

- if volumes equal: $\mathbf{D}_{\parallel}^{\pm,supp} = - (\mathbf{Q}^{\pm})^T \mathbf{Q}^{\pm}$
- Fusion of '±' choice: $\mathbf{D}_{\parallel}^{supp} = \frac{1}{2} (\mathbf{D}_{\parallel}^{+,supp} + \mathbf{D}_{\parallel}^{-,supp})$
- Conserves L1-norm (energy)
- Decreases L2-norm → numerically stable regardless of interpolation method

Simple 2D model problem

- $x \sim$ coordinate within poloidal plane, $z \sim$ toroidal coordinate
- Uniform magnetic field inclined by $\tan \theta = \frac{f h}{\Delta z}$ with respect to grid
- Linear interpolation along x (1d)



- Stencil for support scheme larger
- For $f = 0, 1$, i.e. no displacement, both schemes yield standard second order finite-difference expression

Numerical diffusion

Problem

- Interpolation introduces erroneous numerical coupling among distinct field lines
→ Leads to numerical perpendicular 'diffusion', which is dependent on resolution
- Might overwhelm real (slow) perpendicular dynamics $\chi_{\parallel}/\chi_{\perp} \sim 1 \cdot 10^{10}$
- Extremely high resolutions might be needed

Scaling of numerical diffusion

Action of discrete parallel diffusion operator on mode $u = \exp(ik_x x + ik_z z)$

$$\mathbf{D}_{\parallel}^{\text{naive}} u = \left[-k_{\parallel}^2 - \frac{f(1-f)(k_x h)^2}{\Delta s^2} + \mathcal{O}\left(\frac{(k_x h, k_z \Delta z)^4}{\Delta s^2}\right) \right] u$$

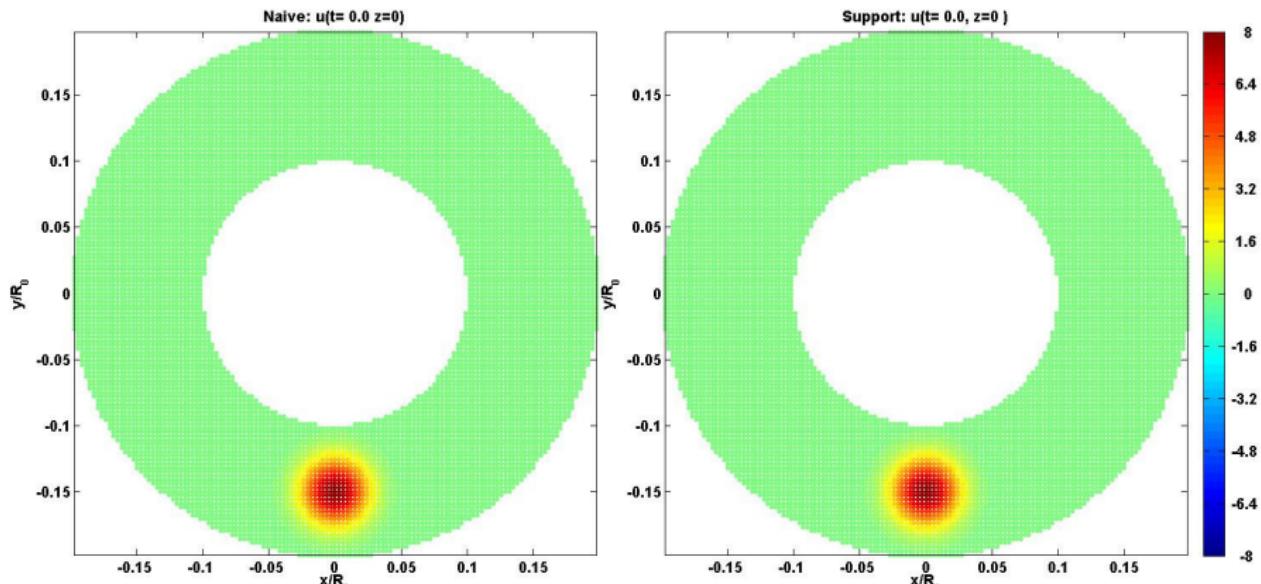
$$\mathbf{D}_{\parallel}^{\text{supp}} u = \left[-k_{\parallel}^2 + \mathcal{O}\left(\frac{(k_x h, k_z \Delta z)^4}{\Delta s^2}\right) \right] u$$

Support scheme exhibits better scaling → numerical diffusion drastically reduced

Numerical diffusion: Example

Example

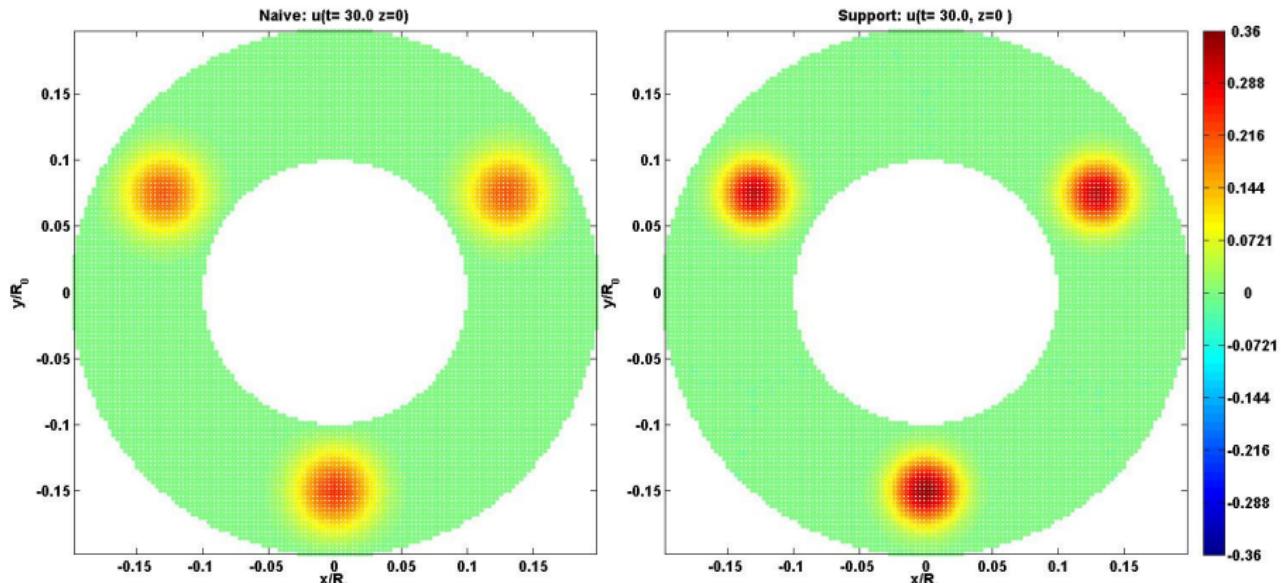
- Parallel diffusion equation $\partial_t u = \chi_{\parallel} \mathcal{D}_{\parallel} u$
- Axial circular configuration with $q = 3$
- Initial state: $u(t = 0, x, y, z) = \exp\left(-\frac{(x-x_0)^2 + (y-y_0)^2}{\sigma^2}\right) \cdot \delta(z)$
- resolution: $N_z = 8$, $\frac{\sigma}{h} \approx 8.3$



Numerical diffusion: Example

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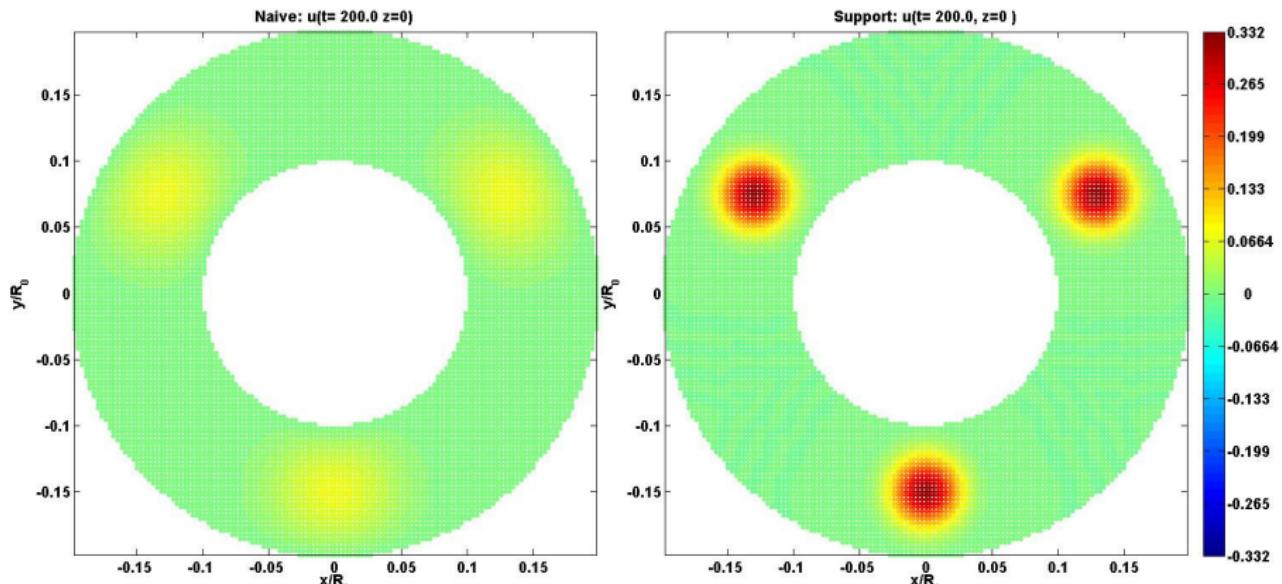
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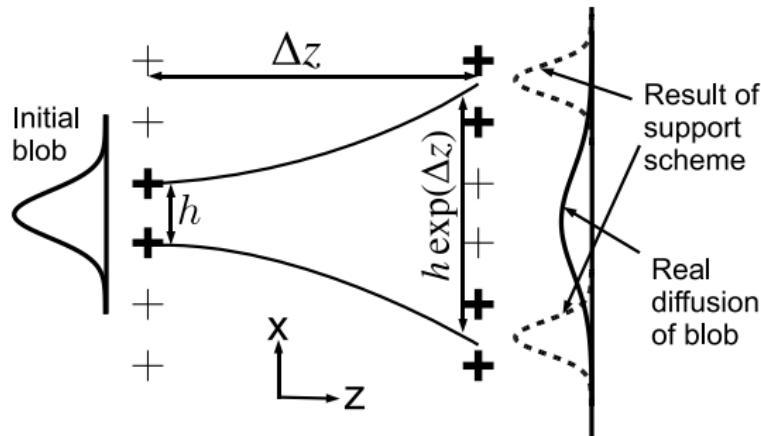
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Map distortion

Magnetic field lines around X-point

- Lowest order expansion: $\mathbf{B} = B_0 [\mathbf{e}_z + \alpha (x\mathbf{e}_x - y\mathbf{e}_y)]$
- Distance between field lines diverges exponentially, i.e. $\delta(z) \propto \exp \alpha z$



- With support scheme information is not only 'taken' but also 'sent' to neighbouring planes
- If points not properly connected erroneous wiggles may arise

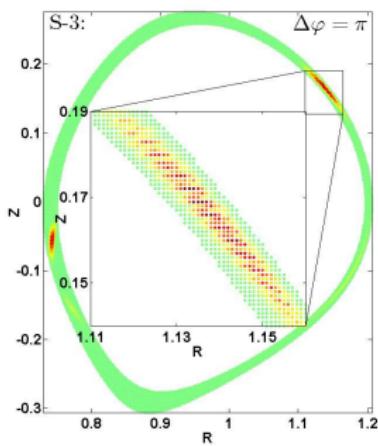
Map distortion: Example

Result of diffusion of blob in flux surfaces close to separatrix:

Support scheme

Interpolation

$$N_\varphi = 2$$



Map distortion: Remedy 1

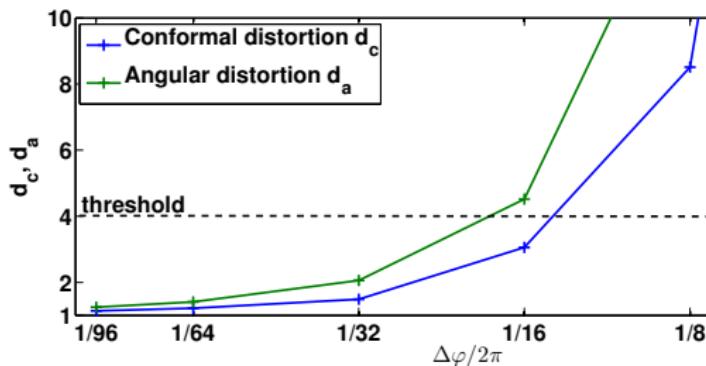
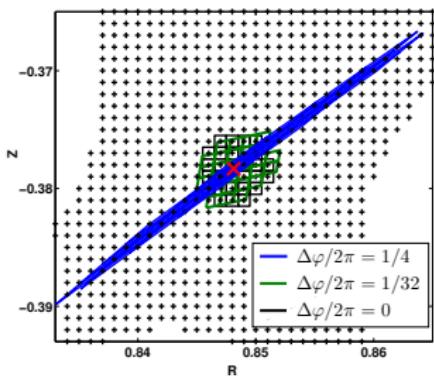
- Quantify distortion via mapped quads:

$$d_c = \max_{i,j} \frac{\text{longest side of mapped quad } i,j}{\text{shortest side of mapped quad } i,j},$$

$$d_a = \max_{i,j} \frac{\text{largest angle of mapped quad } i,j}{\text{smallest angle of mapped quad } i,j}.$$

- Require enough toroidal resolution, such that map distortion remains below threshold

$$d_c, d_a \leq 4$$



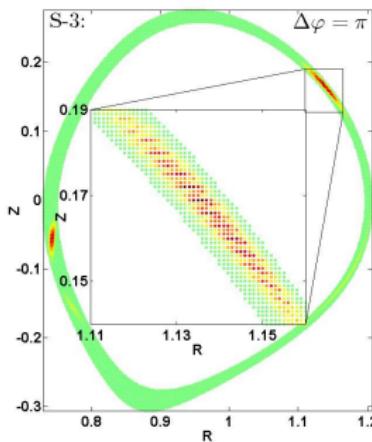
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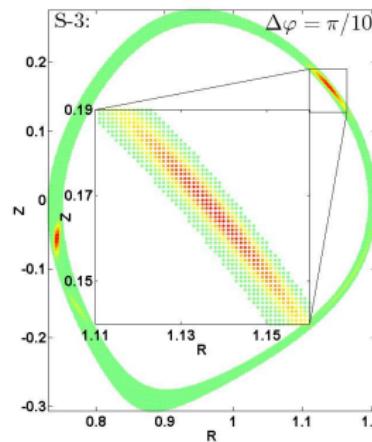
$$N_\varphi = 2$$



Support scheme

Interpolation

$$N_\varphi = 20$$



Note: Tiny oscillations on grid scale might still arise due to change of interpolation stamp [Held15 et al., submitted], could be cured by small amount of high order perpendicular dissipation.

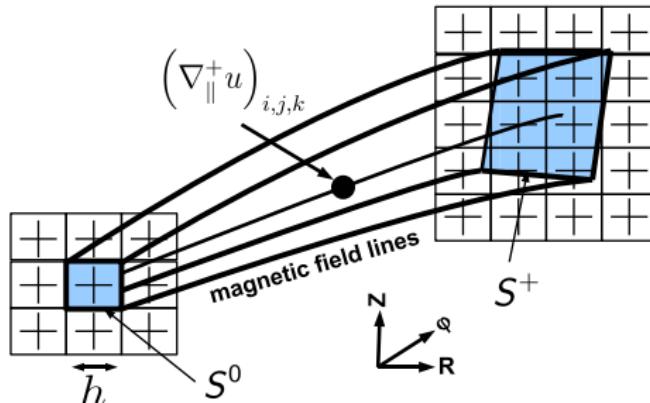
Map distortion: Remedy 2

Change parallel gradient to account for distorted field lines:

Coordinate free representation (Integration)

$$\nabla_{\parallel} u = \frac{1}{B} \nabla \cdot (u \mathbf{B}) = \frac{1}{B} \lim_{V \rightarrow 0} \frac{1}{V} \int_{\partial V} u \mathbf{B} \cdot d\mathbf{S}.$$

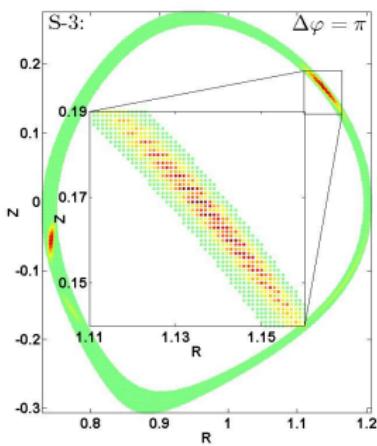
- Mimic surface integral on discrete level
- Integration over toroidal ends of flux box $\nabla_{\parallel}^{\pm} u = \pm \frac{1}{B_V \Delta V} \left[\int_{S^{\pm}} u B_{tor} dS - \int_{S^0} u B_{tor} dS \right]$
- Combination with interpolation



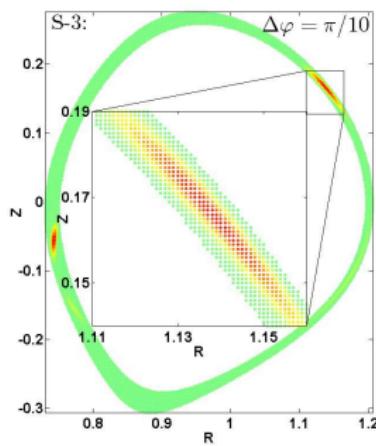
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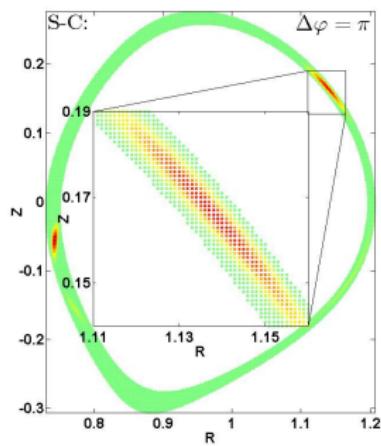
Support scheme
Interpolation
 $N_\varphi = 2$



Support scheme
Interpolation
 $N_\varphi = 20$



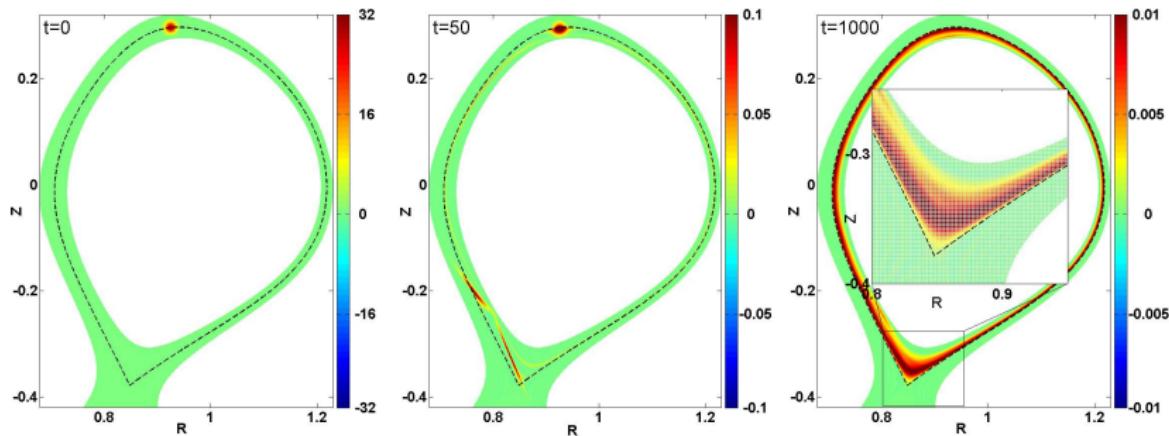
Support scheme
Integration
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Application to separatrix

Example

- Initial state: Gaussian(R, Z)-delta(φ) blob located on separatrix
- resolution: $N_z = 16$, $\frac{\sigma}{h} = 10$
- Boundary conditions: $u = 0$ at divertor plates



- Improvement of parallel boundary conditions is ongoing (e.g. Neumann conditions)

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Hasegawa-Wakatani equations

Normalised equations [*Hasegawa and Wakatani83*]:

Simple self-consistent 3D turbulence model (resistive drift-wave turbulence)

$$\left(\frac{\partial}{\partial t} + \mathbf{v}_E \cdot \nabla \right) n = w_n \mathbf{v}_E \cdot \nabla \Psi(x_{\perp}) + \nu_n \nabla_{\perp}^6 n + \sigma \nabla \cdot [\mathbf{b} \nabla_{\parallel} (n - \phi)],$$
$$\left(\frac{\partial}{\partial t} + \mathbf{v}_E \cdot \nabla \right) \nabla_{\perp}^2 \phi = + \nu_{\phi} \nabla_{\perp}^6 (\nabla_{\perp}^2 \phi) + \sigma \nabla \cdot [\mathbf{b} \nabla_{\parallel} (n - \phi)]$$

- $n = \tilde{n}_e / n_{e0}$: normalised density fluctuation, $\phi = e\tilde{\phi} / T_e$: electrostatic potential

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- ν_n, ν_ϕ : viscosity coefficients
- σ : parallel conductivity, Ohm's law: $\sigma J_\parallel = \nabla_\parallel (n - \phi)$

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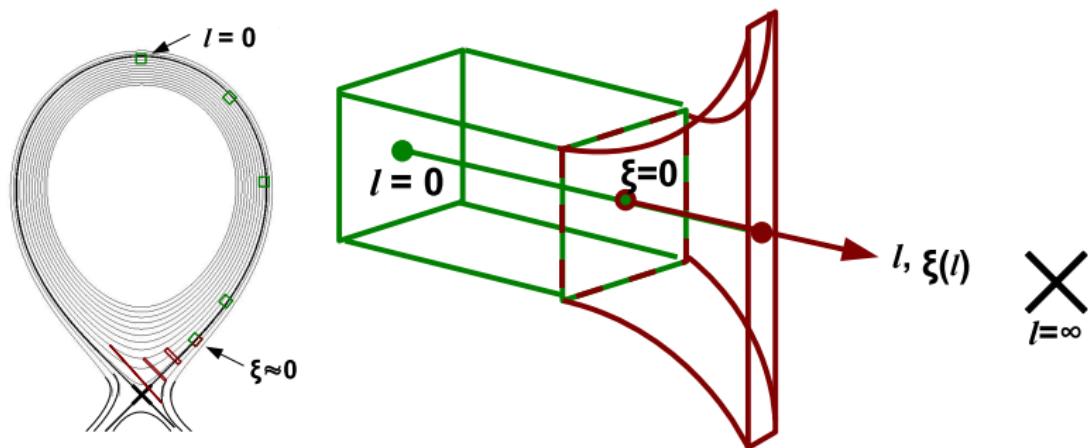
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GRILLIX

- Model implemented for axisymmetric geometry with arbitrary poloidal cross section
- MPI + OpenMP parallelised

X-Point: Theoretical background

Flux box around reference magnetic field line approaching X-point

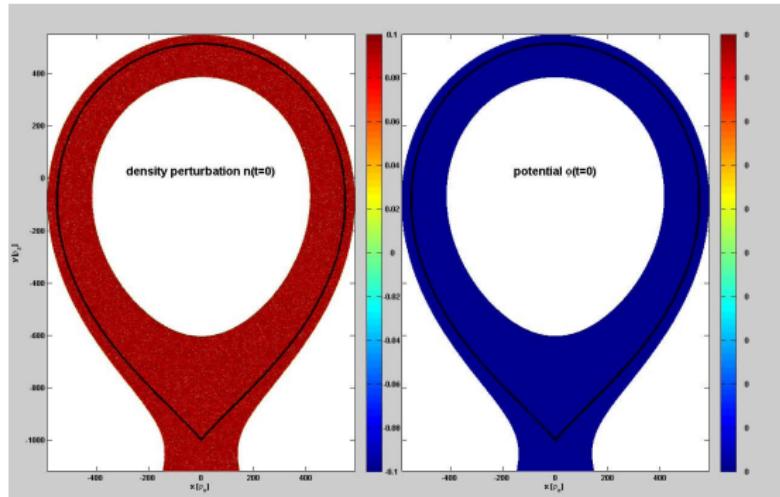


Basic picture [Myra et al.]

- Strong distortion of field-aligned structures towards X-point
- Drastic increase of k_{\perp} towards X-point: $k_{\perp}(I) \xrightarrow[\xi \gg \alpha^{-1}]{} k_{\perp 0} \exp(\alpha \xi(I))$
→ Operators with highest k_{\perp} dependence dominant near X-point, i.e. dissipation
- X-point tends to disconnect structures → increase of k_{\parallel}

Axial diverted geometry²

Initial state

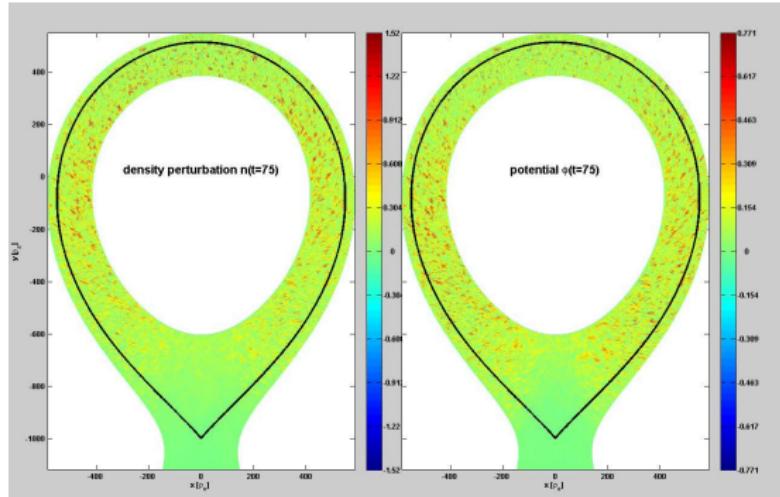


²Parameters reflect roughly:

$$T_e = 80\text{eV} \quad n_{e0} = 4.5 \cdot 10^{13} \text{cm}^{-3}, \quad B = 2.5\text{T}, \quad R_0 = 165\text{cm}, \quad a = 30\text{cm}, \quad L_n = 3.65\text{cm}, \quad M_i = 3670m_e, \quad q_{95} \approx 3/2$$

Axial diverted geometry²

Linear phase



Observations

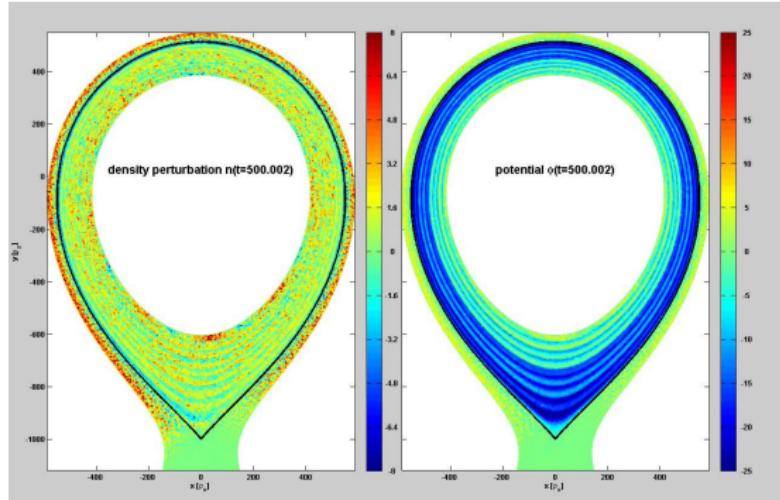
- Strongest effective drive at top
- Fluctuations towards sides driven by parallel currents
- No Fluctuations near X-point

²Parameters reflect roughly:

$$T_e = 80\text{eV} \quad n_{e0} = 4.5 \cdot 10^{13} \text{cm}^{-3}, \quad B = 2.5\text{T}, \quad R_0 = 165\text{cm}, \quad a = 30\text{cm}, \quad L_n = 3.65\text{cm}, \quad M_i = 3670m_e, \quad q_{95} \approx 3/2$$

Axial diverted geometry²

Turbulent phase



Observations

- Automatic development of flux aligned structures
- Clear and sharp separation between open and closed flux surfaces visible

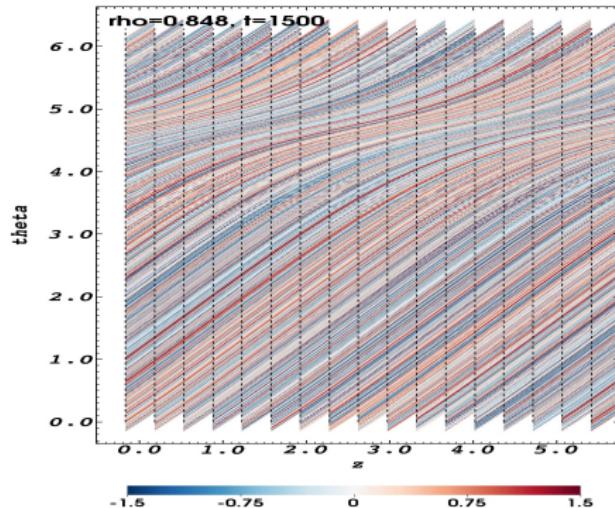
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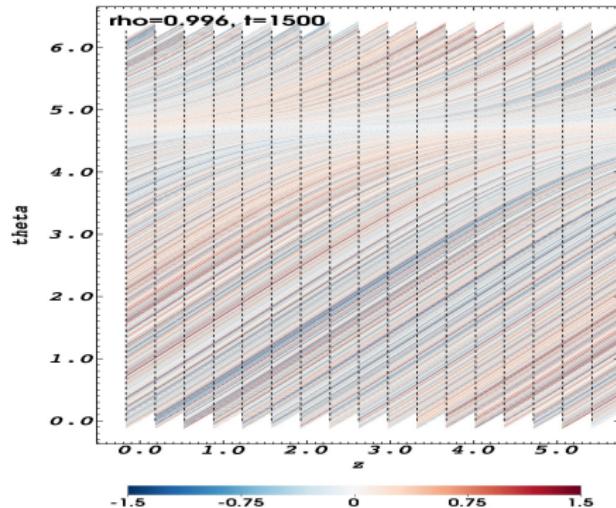
View along magnetic field lines:

Nonadiabaticity $n - \phi$ on flux surface...

...well inside:



...near separatrix



Observations

- structures are numerically smooth along field lines
- Fluctuations damped near X-Point \rightarrow X-point disconnects structures \rightarrow increase of $k_{||}$
- Similar to resistive X-point mode [Myra et al.00]

Table of Contents

1 Introduction

2 Field line map

3 Application to simple turbulence model: Hasegawa-Wakatani

4 Outlook and summary

Recent developments and Outlook

- Extension to full-f:
geometric multigrid solver for nonlinear polarisation ✓

$$\nabla \cdot (n \nabla_{\perp} \phi) = rhs$$

- Additional moments (parallel transport model ✓, thermal fluctuations) towards electromagnetic drift reduced Braginskii model
- Realistic boundary conditions (ongoing)
- Experimental equilibria (eqdsk) ✓
- Extension to 3D geometries, i.e. stellarators (maybe)
- Study of blob propagation in realistic geometry (ongoing → *M.Siccinio*)
- Cross verification against similar codes (GBS, FENICIA, TOKAM3D, FELTOR, BOUT++)
- Investigate effect of geometry on turbulent transport and heat exhaust, relevant for ITER and DEMO

Summary

Field line map

- Cylindrical/Cartesian grid, sparsified in toroidal/axial direction
- FCI: Not based on field/flux aligned coordinates → applicable to separatrix, X/O-points
- Discretisation of perp. operators straight forward (2nd order finite differences)
- Parallel operators via field line tracing and interpolation/integration
- Reduction of numerical diffusion via self-adjoint discretisation with support operator method
- Effects of map distortion identified and resolved (recommendation: use integration-interpolation)

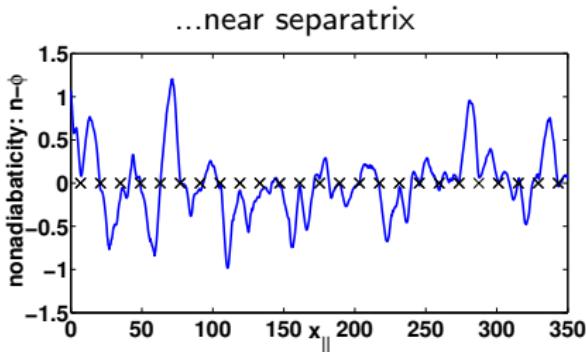
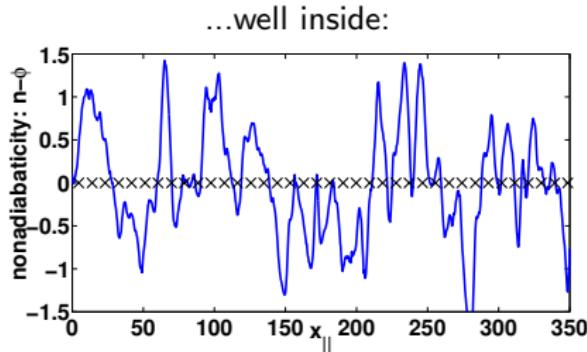
Application to simple turbulence model

- Hasegawa-Wakatani model implemented in parallel code GRILLIX
- Automatic development of field aligned and zonal structures (with Cartesian grid!!)
- Application to X-point geometry:
 - ▶ Strong shear enhances dissipation and leads to disconnection of structures
 - ▶ Increase of k_{\parallel}
 - ▶ Confirmed with GRILLIX

Backup slides

View along magnetic field lines:

...along sample magnetic field line running in flux surfaces...



crosses (x) denote positions where field line passes bottom, i.e. where field line has its closest approaches to X-point

Observations

- Fluctuations strongly damped near X-point
- X-point disconnects structures → increase of k_{\parallel}

→ Similar to resistive X-point mode [Myra et al. 00], though different physical model → Generic property of X-point

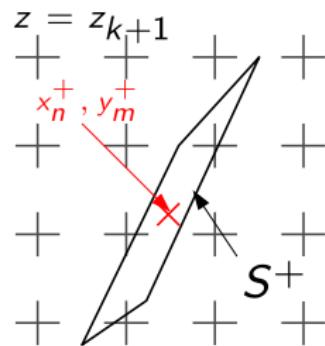
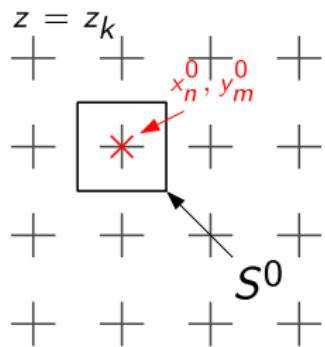
Integration-Interpolation method (detailed)

$$\nabla_{\parallel} u = \frac{1}{B} \lim_{V \rightarrow 0} \frac{1}{V} \int_{\partial V} u \mathbf{B} \cdot d\mathbf{S} \implies \mathbf{Q}^+ u = \frac{1}{B \Delta \mathcal{V}^+} \underbrace{\left[\int_{S^+} u B_{tor} dS_{tor} - \int_{S^0} u B_{tor} dS_{tor} \right]}_{\text{mimic}}$$

$$\int_{S^0} u B_{tor} dS_{tor} = \sum_{n,m=1}^{2X} u(x_n^0, y_m^0, z = z_k) B_{tor}(x_n^0, y_m^0) \frac{h^2}{2^{2X}}, \quad \int_{S^+} u B_{tor} dS_{tor} = \sum_{n,m=1}^{2X} u(x_n^+, y_m^+, z = z_{k+1}) B_{tor}(x_n^+, y_m^+) \Delta S^+,$$

$u(x_n^0, y_m^0, z_k), u(x_n^+, y_m^+, z_{k+1})$ via interpolation, B_{tor} analytically available, $\Delta S^+ = \frac{h^2}{2^{2X}} \frac{B_{tor}(x_n^0, y_m^0)}{B_{tor}(x_n^+, y_m^+)}$

$X=0:$



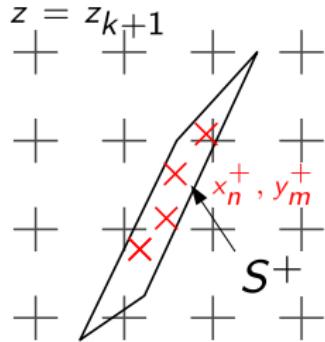
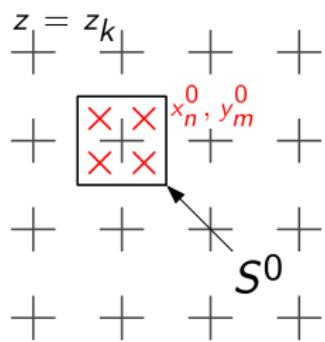
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X=1:



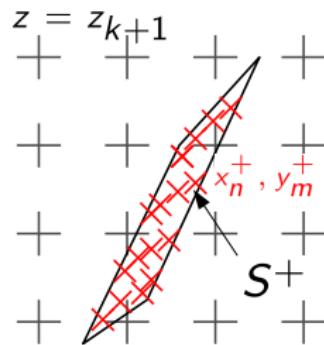
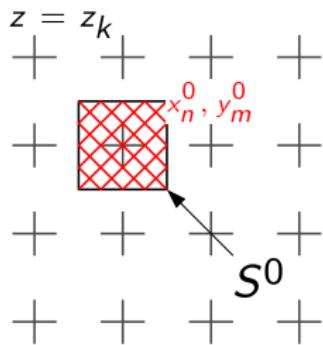
Integration-Interpolation method (detailed)

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$\mathbf{x}=2:$



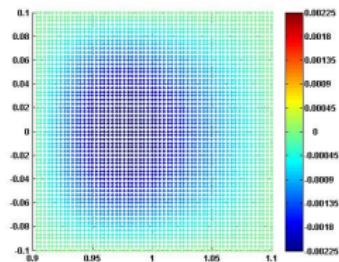
Consistency of parallel diffusion operator in general geometry

Considered case [Held15]:

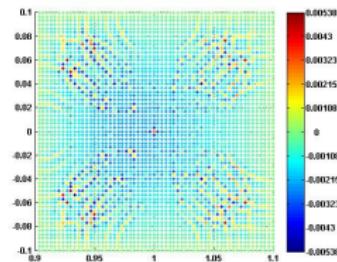
$$\Psi(R, Z) = \cos\left(\frac{\pi}{2}(R - R_0)\right) \cos\left(\frac{\pi}{2}Z\right), \quad u(R, Z, \varphi) = -\Psi(R, Z) \cos(\varphi)$$

Difference to analytic result:

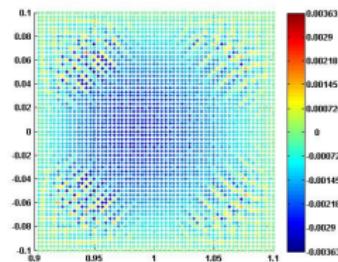
D-3



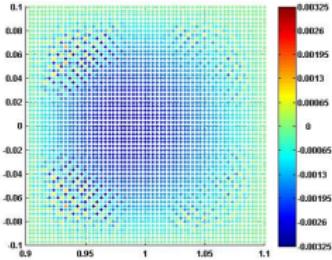
S-3X0



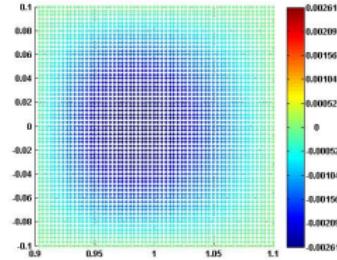
S-3X1



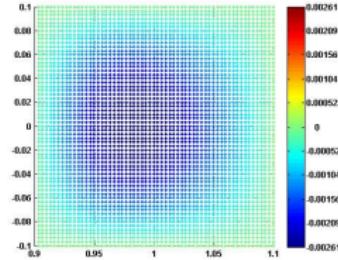
S-3X2



S-3X4



S-3X6

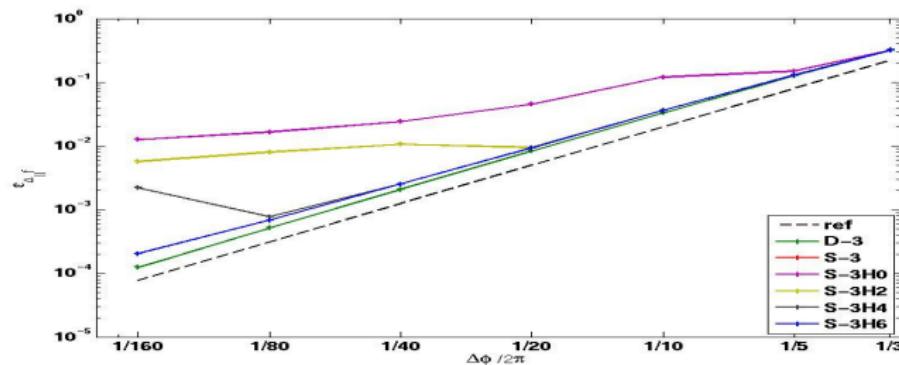


Consistency of parallel diffusion operator in general geometry

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Quantify numerical error $\epsilon_{\Delta_{||} u} := \frac{\|(\mathcal{D}_{||} u)_{\text{numeric}} - (\mathcal{D}_{||} u)_{\text{analytic}}\|_2}{\|(\mathcal{D}_{||} u)_{\text{analytic}}\|_2}$



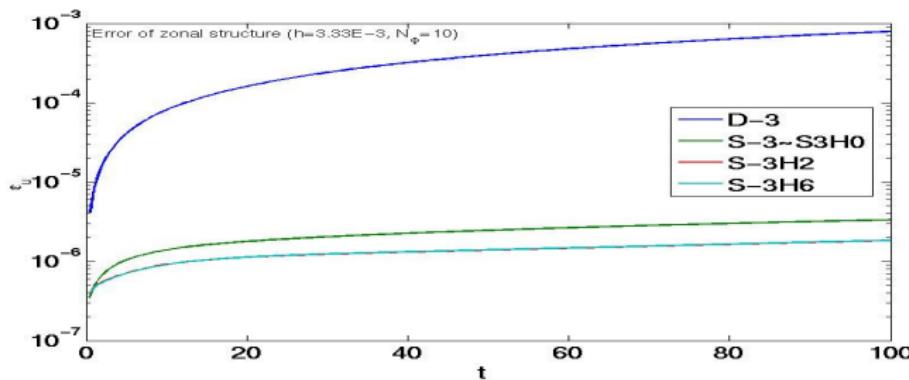
- Second order accuracy in toroidal direction can be achieved
- Prerequisite: sufficiently high perp. resolution, sufficiently high X to account for map distortion

Numerical diffusion in general geometry

Considered case [Held15]:

$$\Psi(R, Z) = \cos\left(\frac{\pi}{2}(R - R_0)\right) \cos\left(\frac{\pi}{2}Z\right), \quad u(R, Z, \varphi, t=0) = 0.1\Psi(R, Z)^2$$

Measure numerical diffusion: $\epsilon_u(t) = \frac{|u(t) - u(t=0)|_2}{|u(t=0)|_2}$

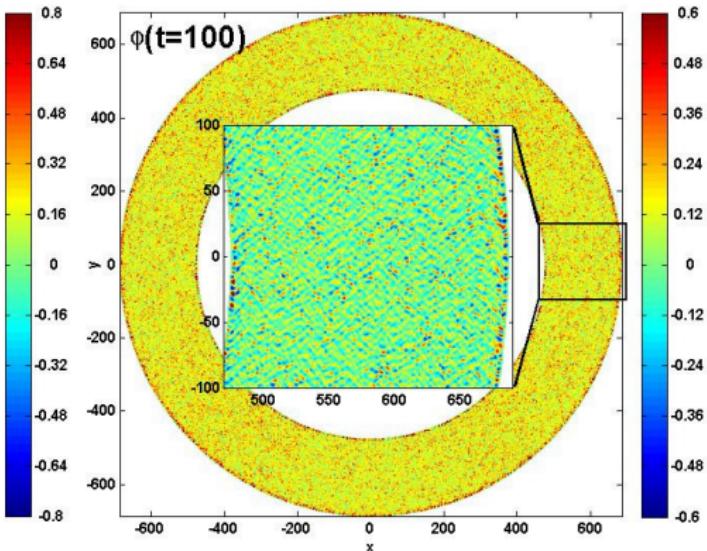
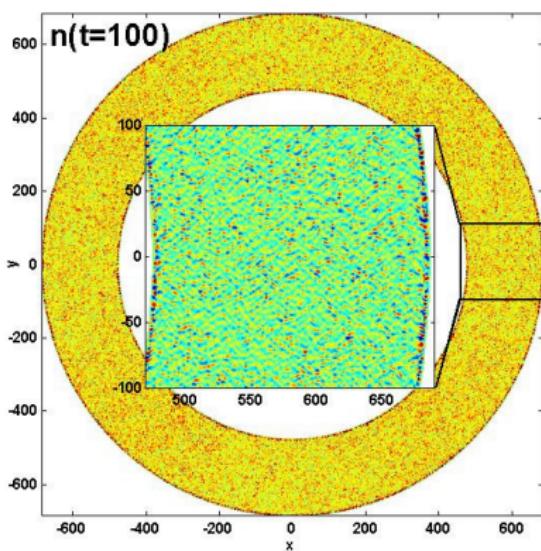


- Lower numerical diffusion with support scheme compared to naive scheme also in general geometries

Axial circular geometry

Demonstration simulation

$$T_e = 80 \text{ eV}, \quad n_{e0} = 4.5 \cdot 10^{13} \text{ cm}^{-3}, \quad B = 2.5 \text{ T}, \quad R_0 = 165 \text{ cm}, \\ a = 30 \text{ cm}, \quad L_n = |n_{e0}/(\nabla n_{e0})| = 3.65 \text{ cm}, \quad M_i = 3670 m_e, \quad q_0 = 3/2, \hat{s} = 0.7$$

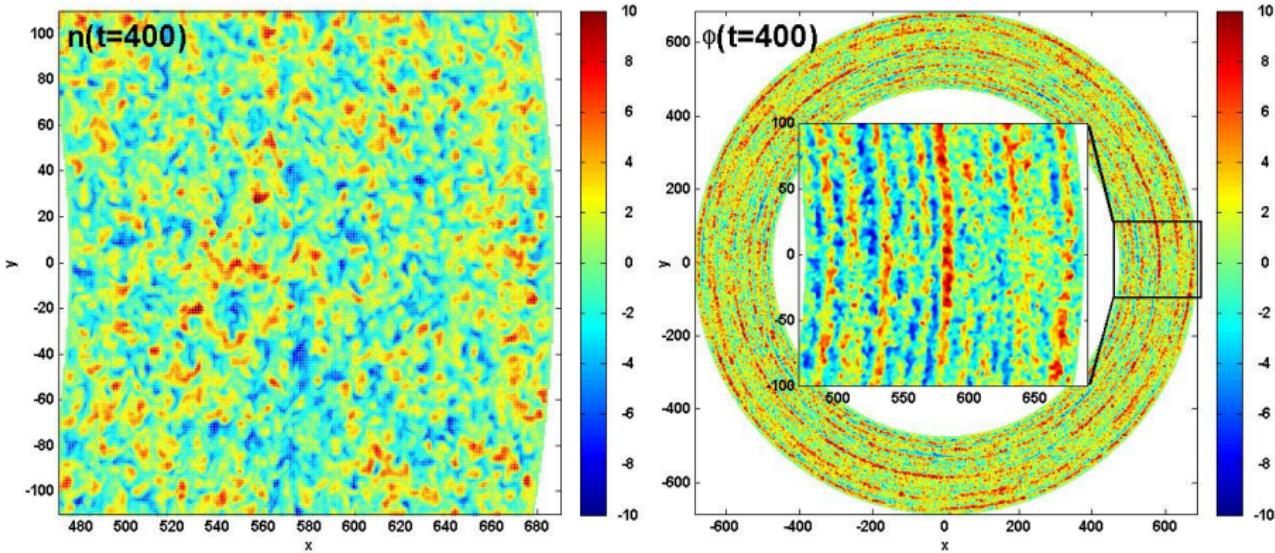


Linear phase: poloidally propagating drift waves

Axial circular geometry

Demonstration simulation

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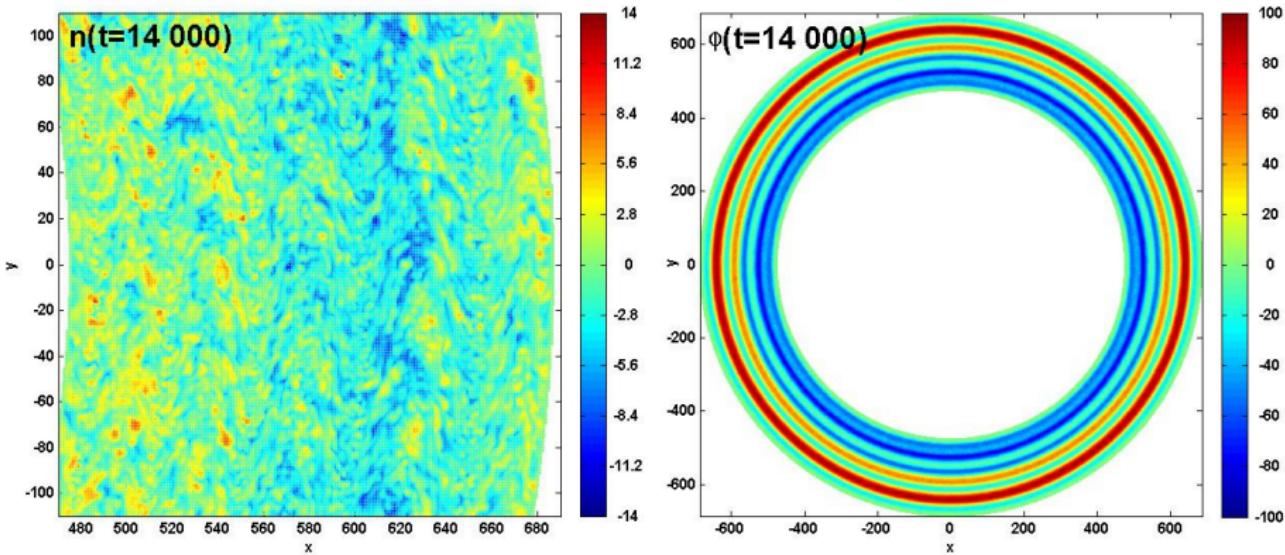


Onset of turbulent phase: Eddy mitosis

Axial circular geometry

Demonstration simulation

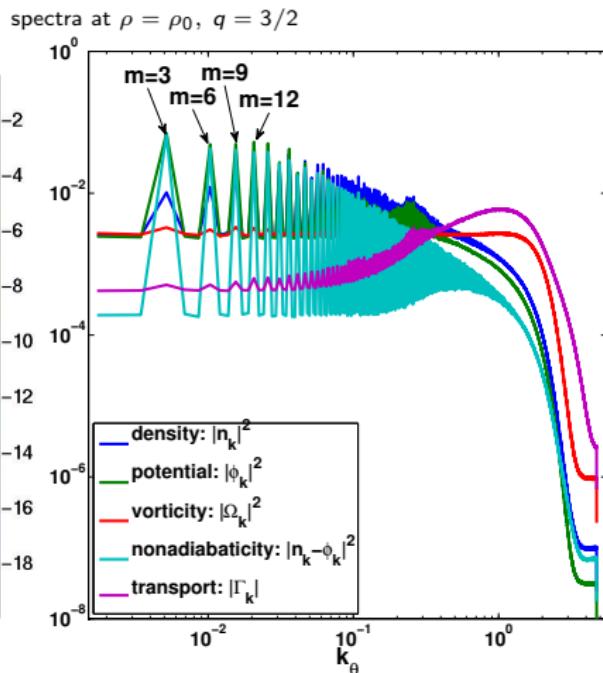
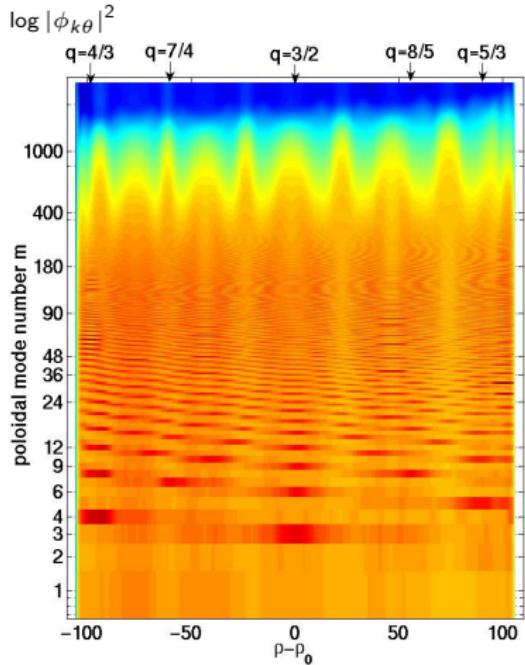
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Saturated phase: Zonal flow

Axial circular geometry

Poloidal spectra:



$k_\parallel \approx 0$ structures on rational surfaces in accordance with geometry

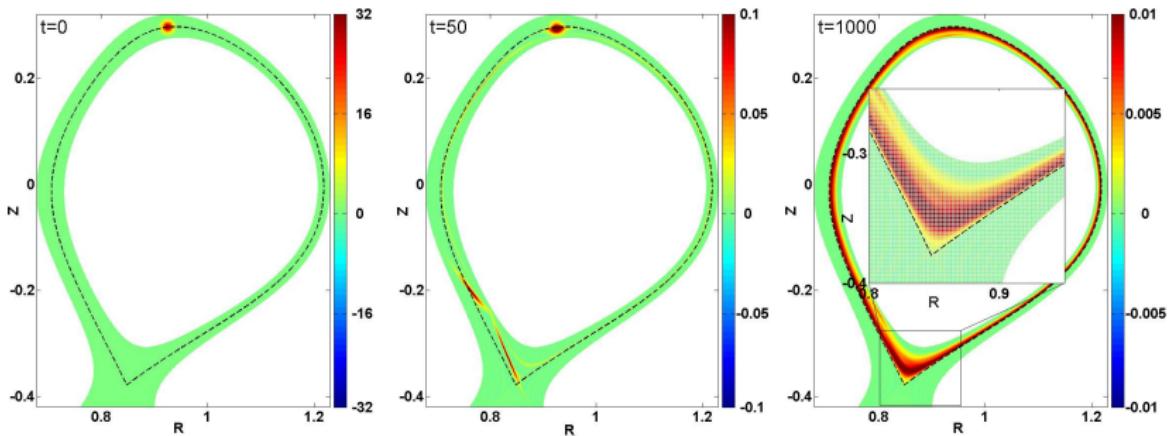
Toroidal Geometry

GRILLIX (A.Stegmeir, see talk on Thursday)

- FCI applied to toroidal geometries
- Discretisation of parallel diffusion
- Based on integral representation for parallel gradient to cope with map distortion

$$\nabla_{\parallel} u = \frac{1}{B} \nabla \cdot (u \mathbf{B}) = \frac{1}{B} \lim_{V \rightarrow 0} \frac{1}{V} \int_{\partial V} u \mathbf{B} \cdot d\mathbf{S}.$$

Simulation of temperature blob in realistic toroidal geometry (parallel diffusion):



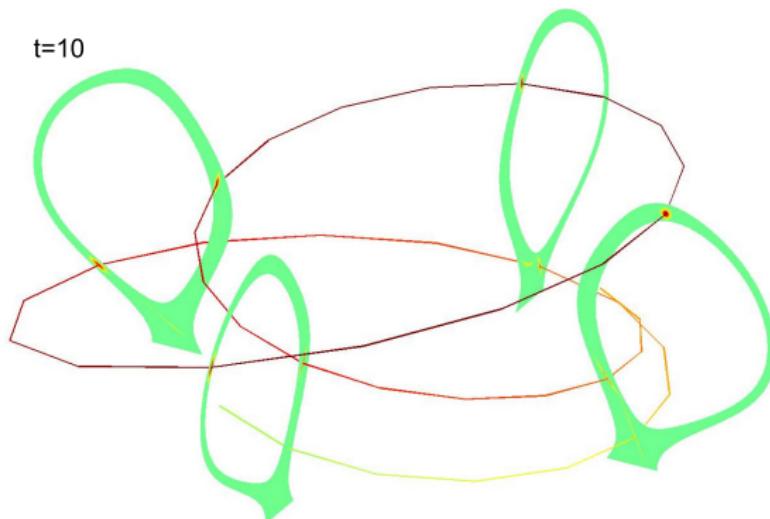
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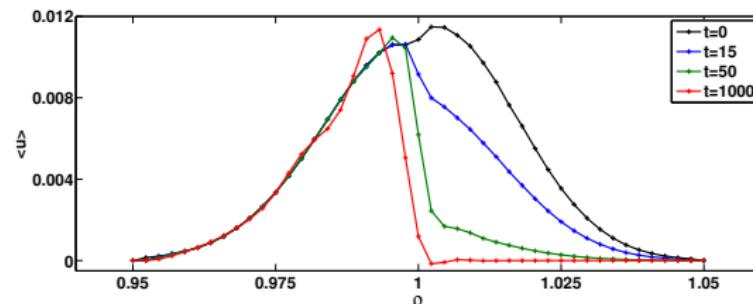
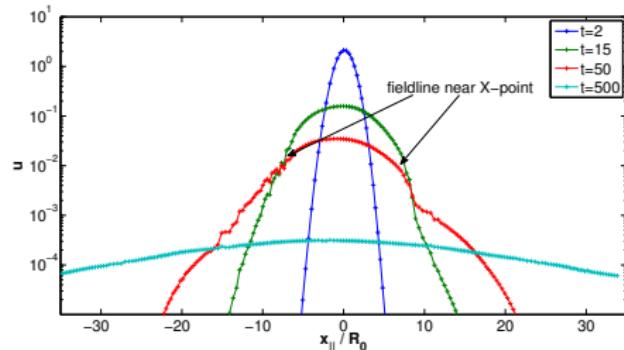
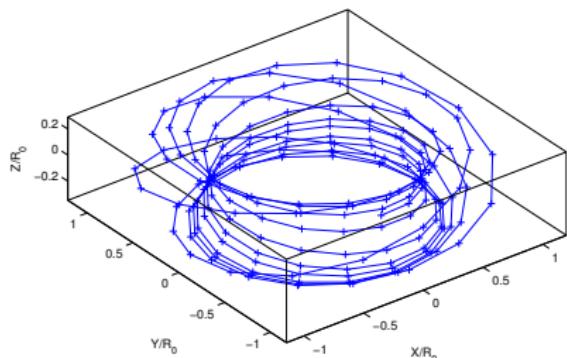
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Simulation of temperature blob in realistic toroidal geometry (parallel diffusion):



Structure along sample magnetic field line



of Flux surface average: